

Online edge coloring

Standard edge coloring:

[Vizing '64] $\forall G, \Delta \leq \chi'(G) \leq \Delta + 1$

[Holyer '81] NP-complete to decide if $\chi'(G) = \Delta$ or $\Delta + 1$.

Online problem: different settings

- vertex arrival
- edge arrival
- random order
- adversarial order
- adaptive order
- Δ known vs unknown.

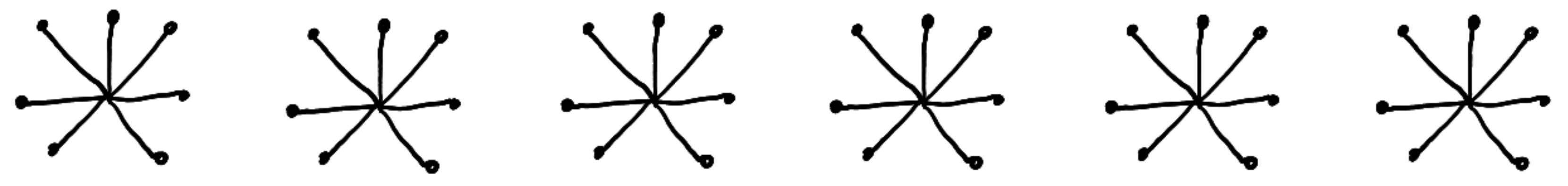
Color the edges progressively without modifications.

[Bar-Noy, Motwani, Naor '92]:

1. Greedy algorithm: use a color not in $N(e)$
 $\leadsto 2\Delta - 1$ colors

2. Cannot maintain a $2\Delta - 2$ edge coloring when $\Delta = O(\log n)$

Start with β $(\Delta - 1)$ -stars



For $\beta \geq (\Delta - 1) \binom{2\Delta - 2}{\Delta - 1}$, Δ of them are colored identically, introduce a vertex dominating their centers.

3. Extension to random order of arrival [Bhattacharya, Gandomi, Wajc '21]

$\exists \beta = 2\Delta \binom{2\Delta - 2}{\Delta - 1} \binom{2\Delta - 1}{\Delta - 1} \leq 4^{O(\Delta)}$ $(\Delta - 1)$ -stars
 + ν adjacent to Δ random stars.

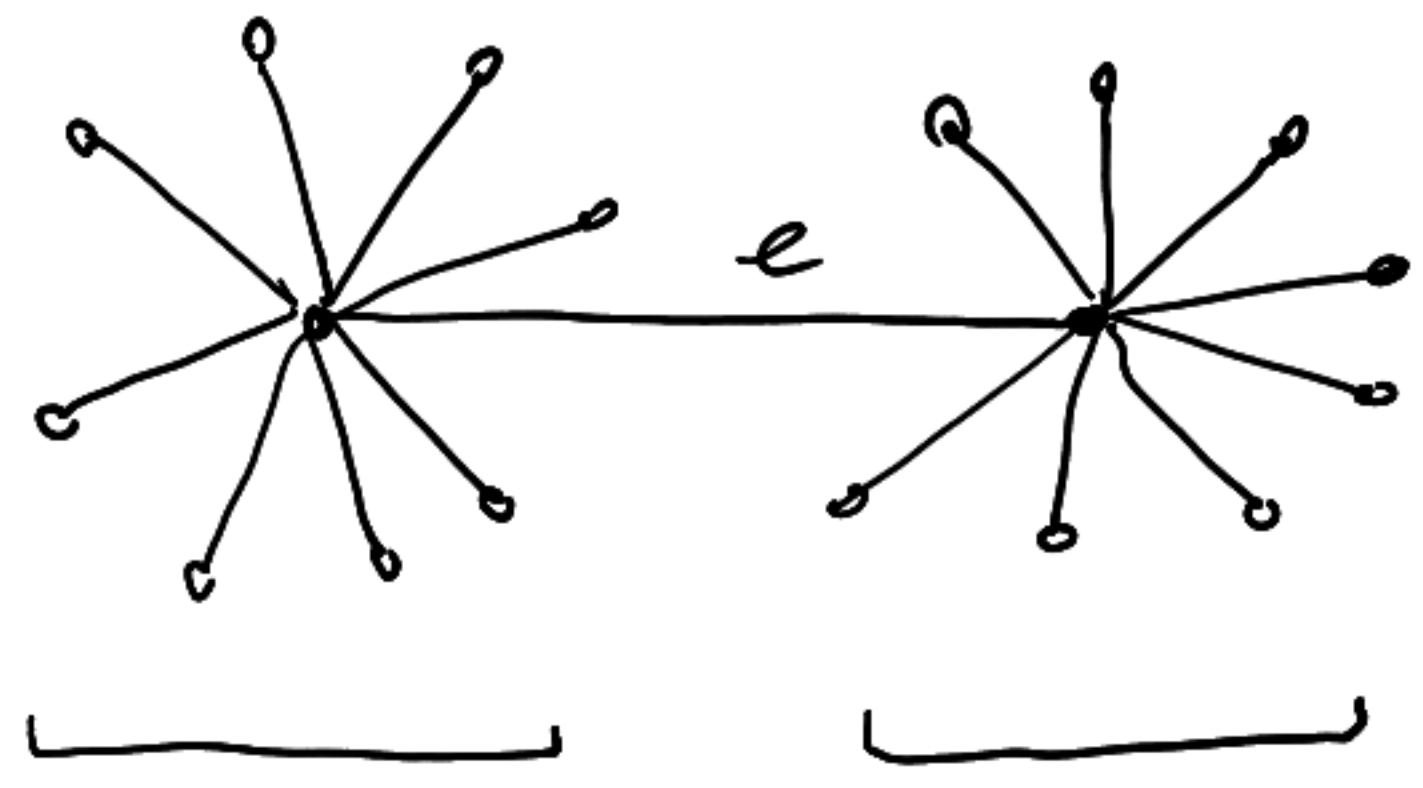
$\mathbb{E}[\# \text{ of stars here before } \nu] = 2\Delta \binom{2\Delta - 2}{\Delta - 1} \leadsto \text{pigeon hole.}$

What competitive ratio can we achieve when $\Delta = \omega(\log n)$?

Conjecture: the following algorithm can do $\Delta + O(\sqrt{\Delta \log n})$ with good probability when $\Delta = \omega(\log n)$

Color each edge with a random color among the available colors.

Tight:



reveal first, reveal second, reveal e

$k = \Delta + \Omega(\Delta)$ to have constant probability of success.

Random order edge-arrival:

[Aggarwal, Motwani, Shah, Zhu '03]:

$(1 + o(1))\Delta$ for multigraphs with $\Delta = \omega(n^2)$

[Bahmani, Mehta, Motwani '12]: 1.26Δ when $\Delta = \omega(\log n)$

[Bhattacharya, Gandomi, Wajc '21]: $(1 + o(1))\Delta$ when $\Delta = \omega(\log n)$
using Nibble method.

Standard mibble method for distributed coloring: In each round,

each vertex select a random ϵ fraction of its incident edges.

The selected, choose a random color available.

If there is a conflict, do nothing.

Why does it work?

- Each edge fails with probability $O(\epsilon)$

\Rightarrow the uncolored subgraph decreases its degree w.h.p. at rate $1 - \epsilon$

- After $t_\epsilon = O\left(\frac{\log(1/\epsilon)}{\epsilon}\right)$ rounds, uncolored degree = $\text{poly}(\epsilon)$

we apply a greedy algorithm.

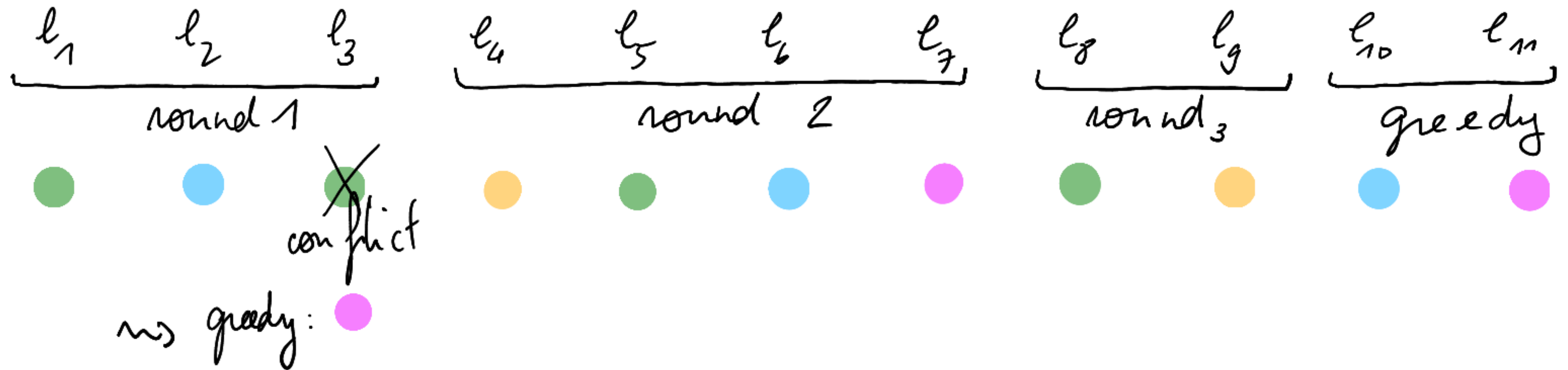
Easier analysis:

- Sample the edges independently at rate ϵ .

- When conflict, color greedily directly

- If conflict, remove the color of the palette of the vertices.

Online version:



Only difference: no knowledge of the rounds and choices within rounds are not simultaneous.

- Virtual rounds of the appropriate length, update the color palette of the vertices at the end of each round.
- No conflict for the first edge using a color.

Adversarial vertex arrival

[Cohen, Peng, Wajc '19]

• $(1 + o(1)) \Delta$ for bipartite graphs with one-sided vertex arrival.

• Reduction from online edge coloring to online matching

• When Δ is unknown, cannot do better than

$\left(\frac{e}{e-1}\right) \Delta$ even for bipartite graphs, one-sided vertex arrival

[Saberi, Wajc '19]:

• online reduction from general graphs to bipartite graphs against oblivious

• $(1.9 + o(1)) \Delta$ for general graphs.

Adversarial edge arrival

[Kulkarni, Liu, Sah, Sawhney, Tarkenton 21]

$$\left(\frac{e}{e-1} + o(1)\right) \Delta \quad \text{when} \quad \Delta = \omega(\log n)$$

$$\approx 1.58$$

(Against oblivious)

Sketch of the proof:

Reduction to an online matching problem on tree-like graphs

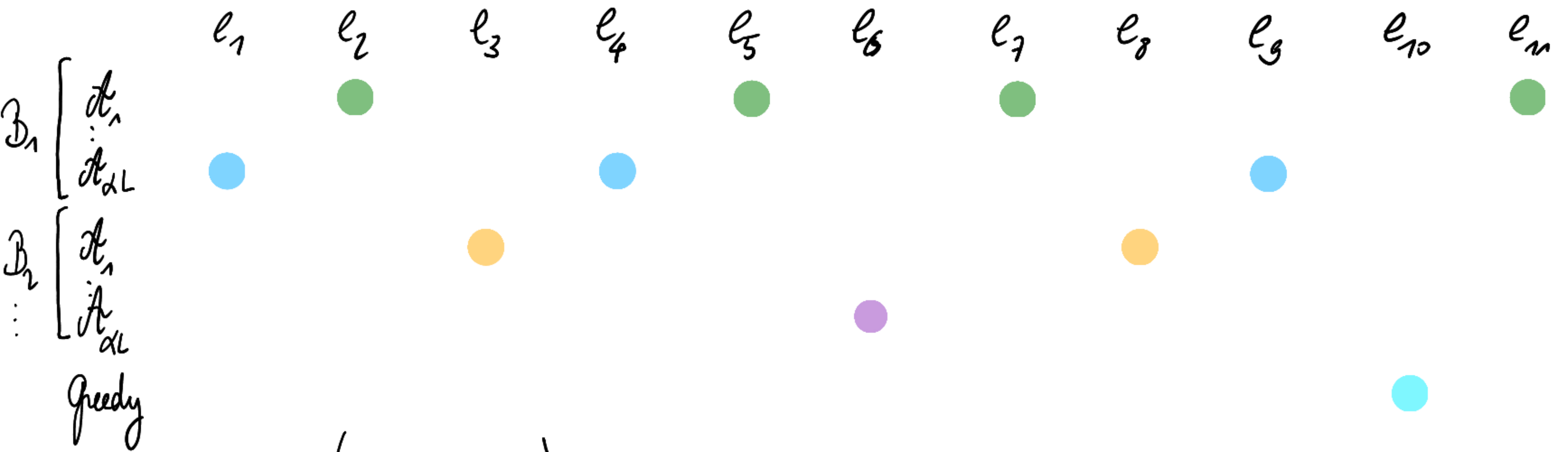
Thm: α an online matching algorithm, $\alpha \geq 1$ s.t.

$\forall G, \Delta(G) = \Omega(\log n)$, α matches each edge with marginal probability $\frac{1}{\alpha \Delta(G)}$.

Then, there is an online edge-coloring algorithm α' , s.t.

$\forall G, \Delta(G) = \omega(\log n)$, α' produces a $\left(\alpha + O\left(\left(\frac{\log n}{\Delta}\right)^{1/4}\right)\right) \Delta$ coloring with high probability.

Idea of the proof: inductive run of A .



- $L = O(\sqrt{\Delta \log n})$
 H : uncolored subgraph.

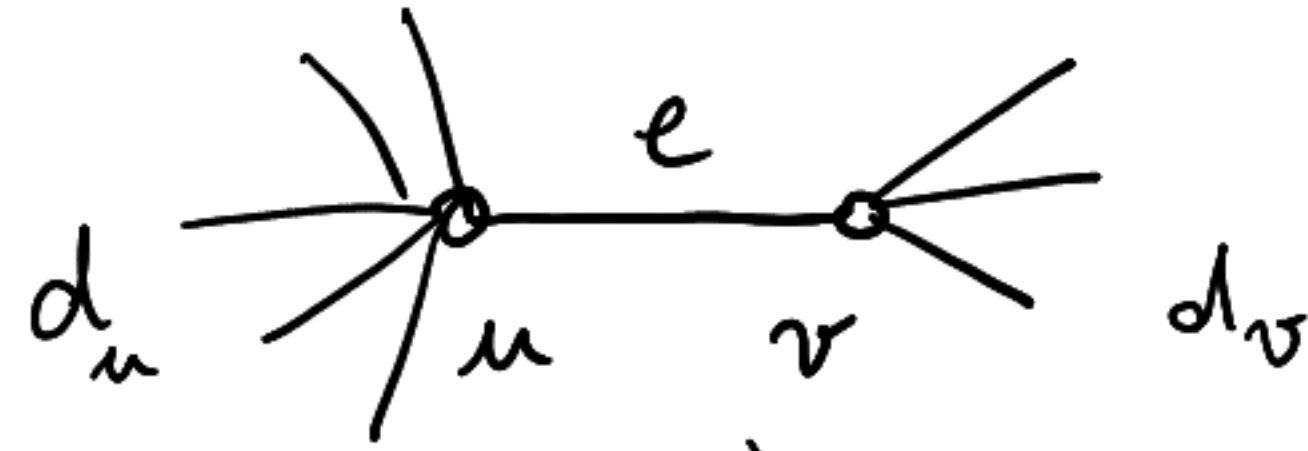
• Claim: If $\Delta(H) = \Delta_i \geq O(\sqrt[4]{\Delta^3 \log n})$, After B_i ,

$$P[\Delta(H) \geq \Delta_i - L(1 - o(1))] \leq \frac{1}{n^2}$$

• While $\Delta_i := \Delta - (i-1)L(1 - o(1)) \geq O(\sqrt[4]{\Delta^3 \log n})$, apply B_i

$\leadsto \frac{\Delta}{L}$ rounds using αL colors + greedy with $H = o(\Delta) = (\alpha + o(1))\Delta$ colors 9

Online matching on trees: Match each edge with marginal probability $\frac{1}{c}$



$$P(u \text{ is not yet matched}) = \left(1 - \frac{d_u}{c}\right)$$

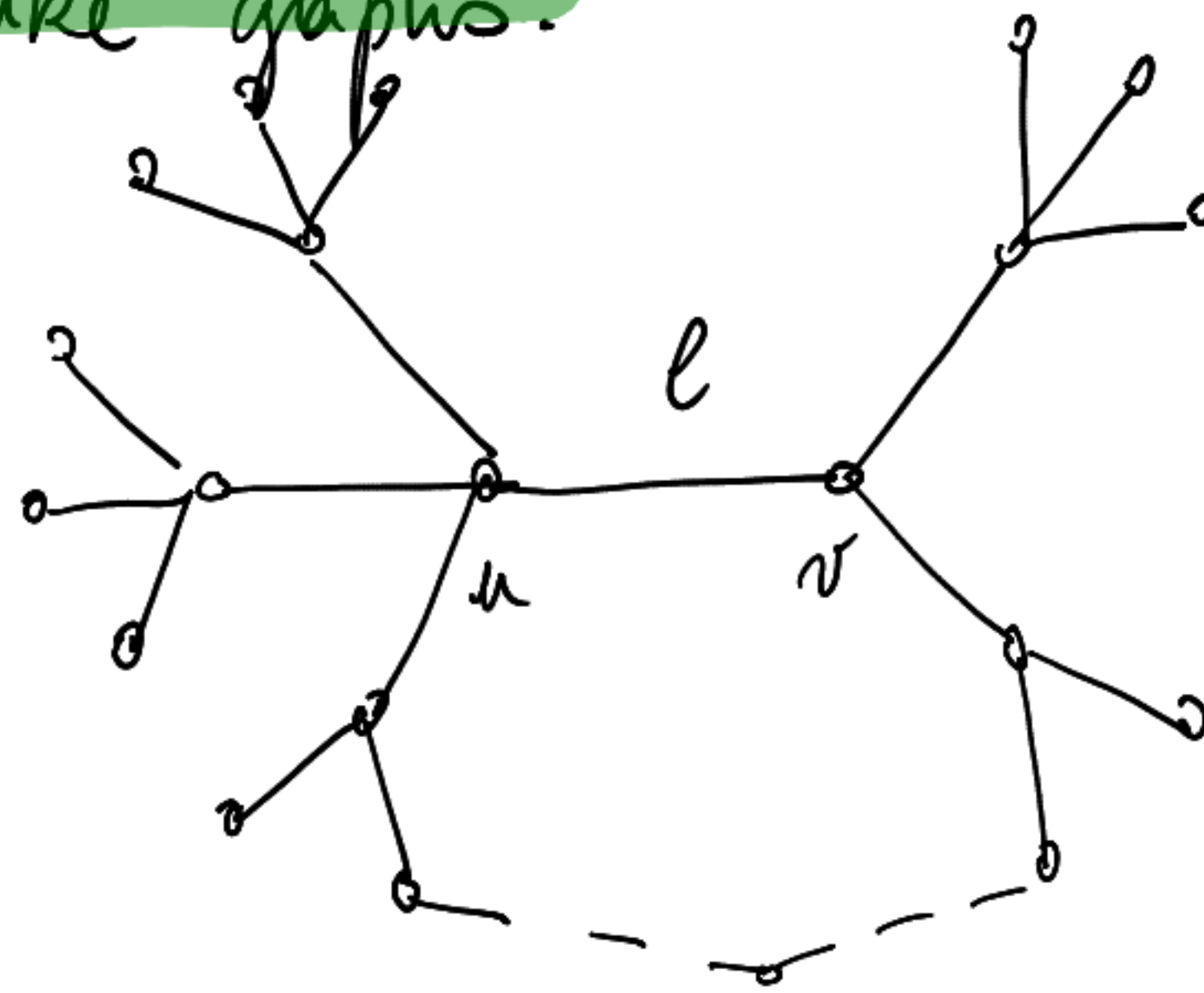
$$P(v \text{ is not yet matched}) = \left(1 - \frac{d_v}{c}\right)$$

independent in trees

Match uv with probability p s.t.

$$\left(1 - \frac{d_u}{c}\right) \left(1 - \frac{d_v}{c}\right) p = \frac{1}{c}$$

From trees to treelike graphs:



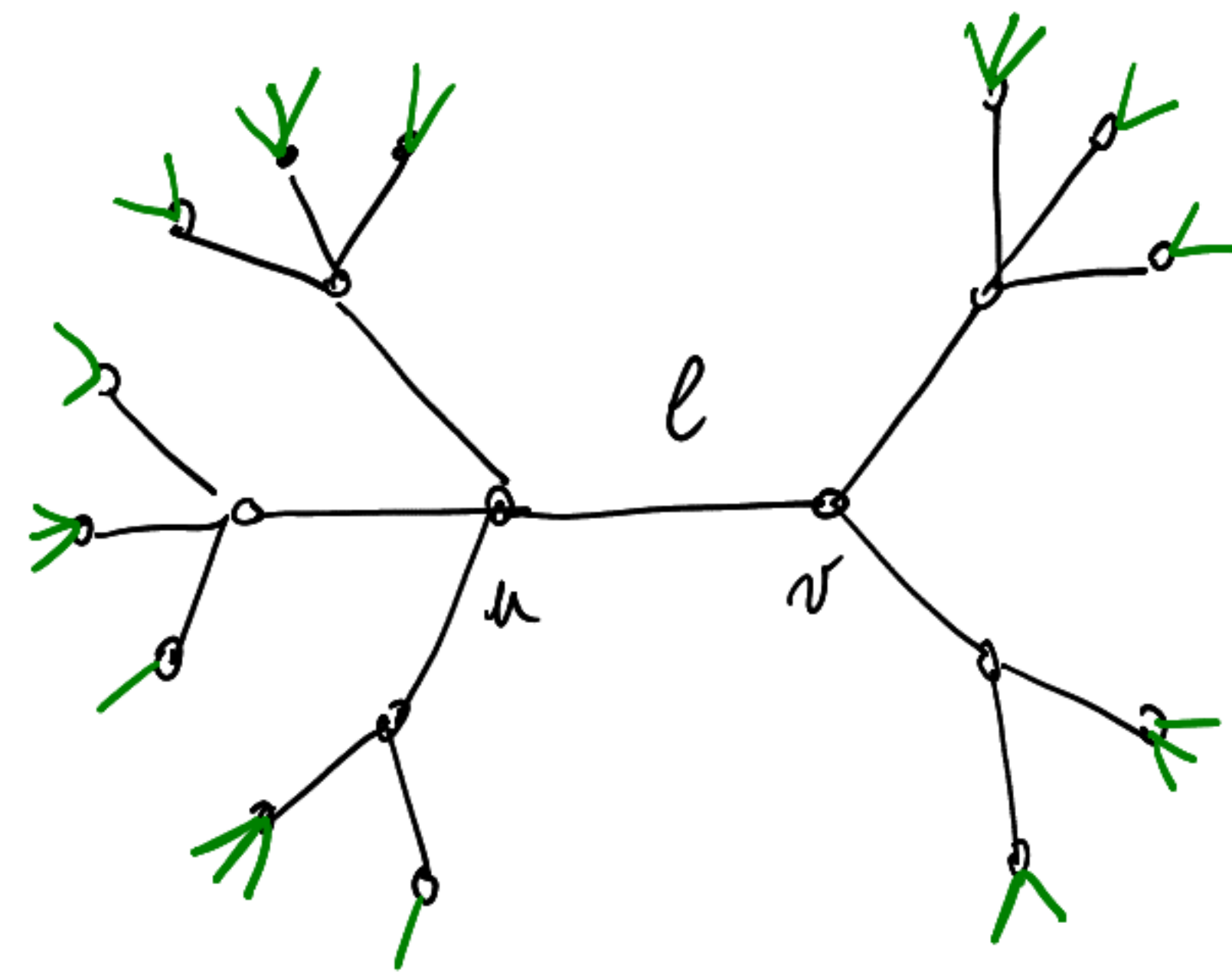
What happens far away should not affect e !

Decay of correlations:

$\tau_T = N_d(e)$ for some e .

$$\partial T = E(G, T, T)$$

Edge matching game: edges of $T \cup \partial T$ appear progressively. If $e_i \in \partial T$, the adversary chooses whether e_i is matched.



Goal of the adversary: minimize $P(e \text{ is matched})$.

Observation 1: if f is on a $e-g$ path and f appears before g , then g has no impact.

Monotonicity property: for d odd, the optimal strategy of the adversary is to unmatch all edges of ∂T .

If $C > \left(\frac{e}{e-1} + o(1)\right) \Delta$, when d grows, $P(e \text{ is matched} \mid \partial T) \xrightarrow{\text{exp fast}} \frac{1}{C}$.

Discussion:

- Reduction to locally tree-like graphs is something more general:
Given G of max degree Δ and arbitrarily large girth, can one partially edge color G with Δ colors s.t. each edge is colored with probability $1 - o_\Delta(1)$?

Greedy approach: $\frac{1}{2} - o_\Delta(1)$

Matching based approach $\frac{e-1}{e} - o_\Delta(1)$

- The $\frac{e}{e-1}$ barrier is tight Kulkarni et al. matching approach.

Maybe a "local" algorithm like theirs but with more than two states can work, but in statistical mechanics, these are much harder to analyse.

+ Monotony seems hard

\rightarrow What is the adversarial strategy on the boundary?

Connection with Glauber dynamics.

Conclusion and perspectives

1. Ban Noy et al conjecture true for
 - adversarial vertex arrival
 - random order edge arrival

Best known bound for adversarial edge arrival: $\left(\frac{e}{e-1} + o(1)\right) \Delta$

Conjectured to be true for oblivious adversary but not adaptive.

2. What happens when Δ is unknown?

[Cohen, Peng, Naji '19] For adversarial vertex arrival, this is a harder problem, no online algorithm can do better than $\left(\frac{e}{e-1}\right) \Delta$

Is this something more general?

Thanks !